

Application Note: Building freETarget Basic

SUMMARY

One goal of freETarget was to make electronic targets accessible to a wide range of people around the world. freETarget Basic is the simplest construction that can be made using local material. The document is organized as:

- Building the target frame
- Installing the circuit
- Downloading the PC software
- Starting up
- Trouble shooting

The example shown here is made from plywood and plastic. You may choose to assemble it with different materials.

REQUIRED

- freETarget circuit
- Cardboard or similar material
- Internet connection
- Hand tools
- Patience

IMPORTANT

This application note is provided as a minimal means of building freETarget. Cardboard has **NO** protection from pellets or bullets. Shooting outside of the target area can have severe consequences to the circuit or surrounding material.

The reader is responsible for any damage that could be caused by shooting into this target holder.

INTRODUCTION

freETarget is an open source project to provide shooters with a low cost electronic target. One of the objectives is that the materials needed to make the target will be sourced from around the world and will be dependent on what is available locally. To do this, much of the initiative to tailor the construction to your skills and parts availability comes from people like you.

This application note provides the basics to construct freETarget from cardboard. Read all of the instructions before starting. You may have to change materials or operations based on what you have at hand.

BUILDING THE TARGET FRAME

The target frame holds the target and sensors in the correct position to record the shot. The assembly can be made of anything local, such as

- Cardboard
- 3D Printed sensor mounts
- Hot glue or similar
- Duct tape or similar
- Paper Clips

A side view of the target assembly is shown in Figure 1.

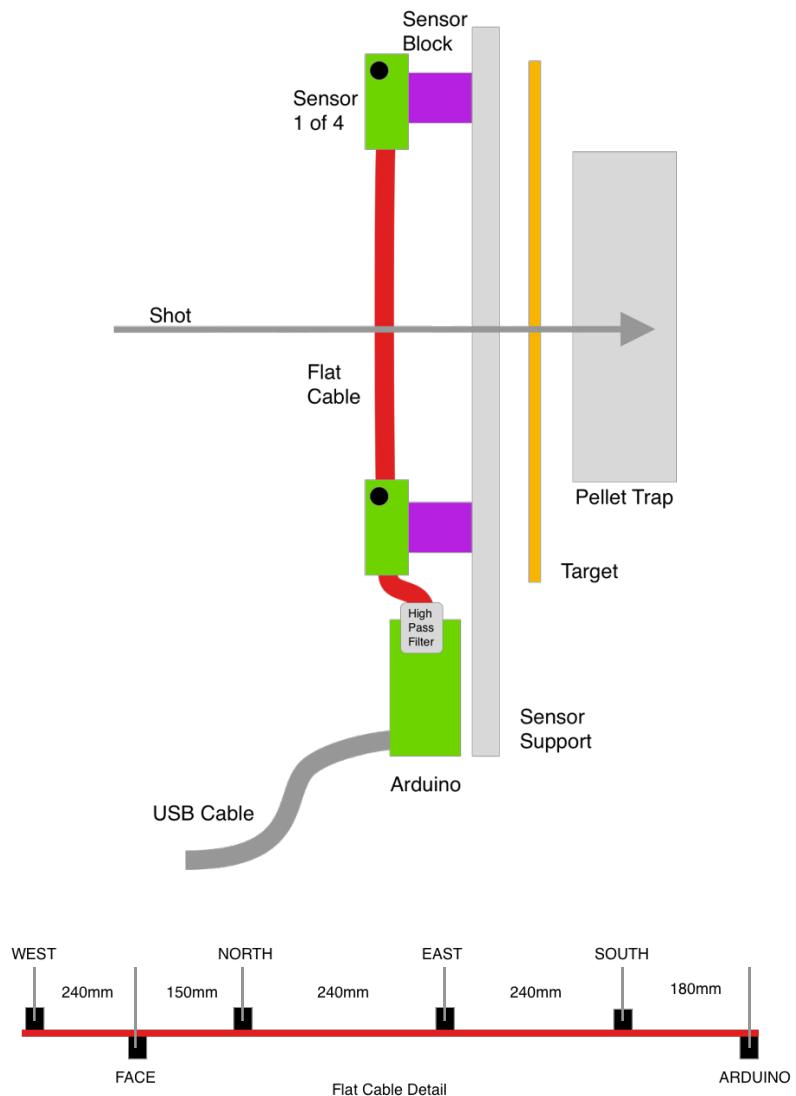


Figure 1: freETarget Layout

Item	Description	Notes
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Sensor	Four microphones located around the target to detect the shot	Pay careful attention to the locations stenciled on the circuit board. Sensors may be located anywhere between the front face and pellet trap.
Flat Cable	Routes from the Arduino board to the sensors	End marked with an A is the Arduino end of the cable
High Pass Filter	Small board that installs between the flat cable and Arduino	Used to attenuate report from gun
Sensor Block	Mounting block to hold sensor parallel to direction of shot	May be any non-conductive material.
Sensor Support	Back frame to hold the sensors in the correct location and orientation	
Target	Target	May be located anywhere between the front face and pellet trap.
Pellet Trap	Pellet Trap	Used to collect pellets after shooting. May be omitted if shooting on a range with a berm.
USB Cable	Fifteen meter USB cable	May be purchased locally or on line

Start marking the heavy cardboard as shown in Figure 2.

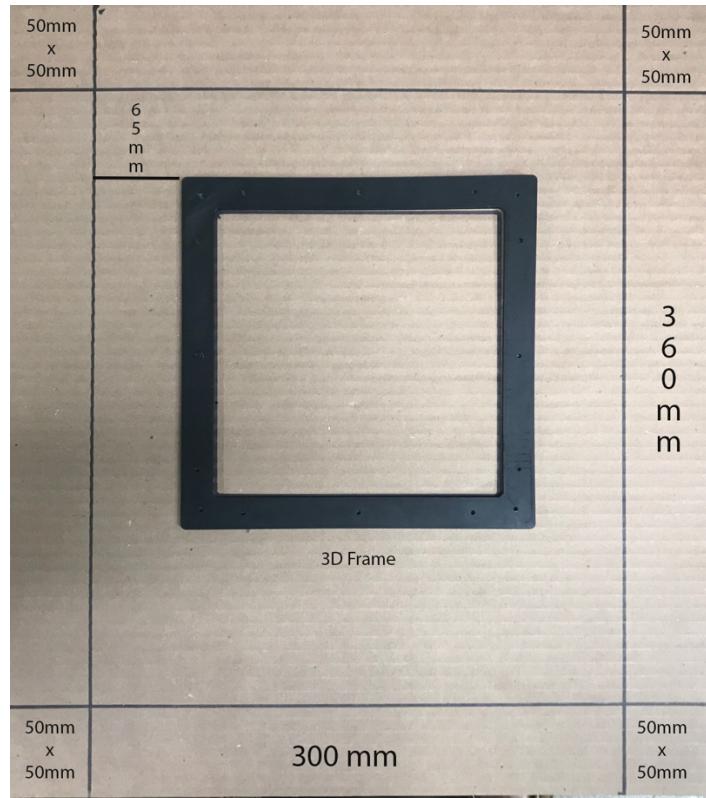


Figure 2: Marked Cardboard

Cut out the corners and target hole as illustrated in Figure 3. From the opposite side, cut or score the cardboard along the perimeter lines.



Figure 3: Cut Cardboard

Along the scored lines, fold the cardboard inward to form a box as shown in Figure 4. Hold the corners in place with tape or glue.



Figure 4: Folded Box

Using hot glue or some adhesive, locate the 3D Printed parts as shown in Figure 5.

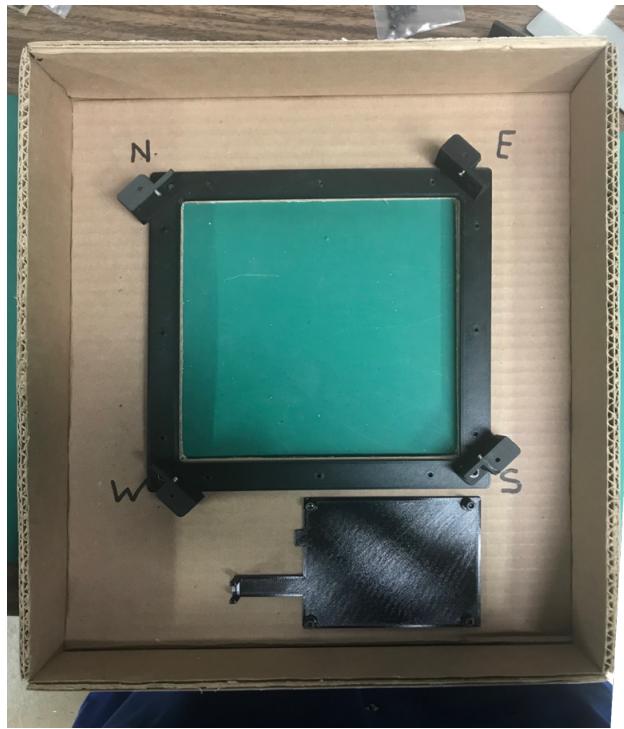


Figure 5: 3D Printed Parts Installed

Install the circuits per Figure 6. Pay attention to installing the sensors in the correct location, ex North to North...



Figure 6: Installed Circuits

The last step is to attach the target holder. Attach two paper clips to a target and center the target over the hole. Hot glue the paper clips in place. Mark the four corners of the target to consistently locate the target. See Figure 7 for an illustration



Figure 7: Target Paper Clips

Locate the bullet trap behind the target holder.

DOWNLOADING AND INSTALLING PC SOFTWARE

Click the link below to go to the downloads page

<https://free-e-target.com/downloads/>

Look for the PC Software section and download the software (Figure 8)

PC Software

The source files are available on the Github, and you can build your own using the VisualStudio hobby edition.

The most recent version can be downloaded here:

[freetarget-1.13.0_2](#) [Download](#)

Once you download it, unzip the files and follow the instructions.

Figure 8: Download Software

Unzip the software and install on your PC.

Connect the USB cable between the target holder and the PC.

STARTING UP

Launch the PC program and look for the setup icon (GEAR WHEEL) in the upper right corner (See Figure 9)



Figure 9: Setup Icon Location

Enter all of the setup information needed in Figures 9, 10, 11, and 12

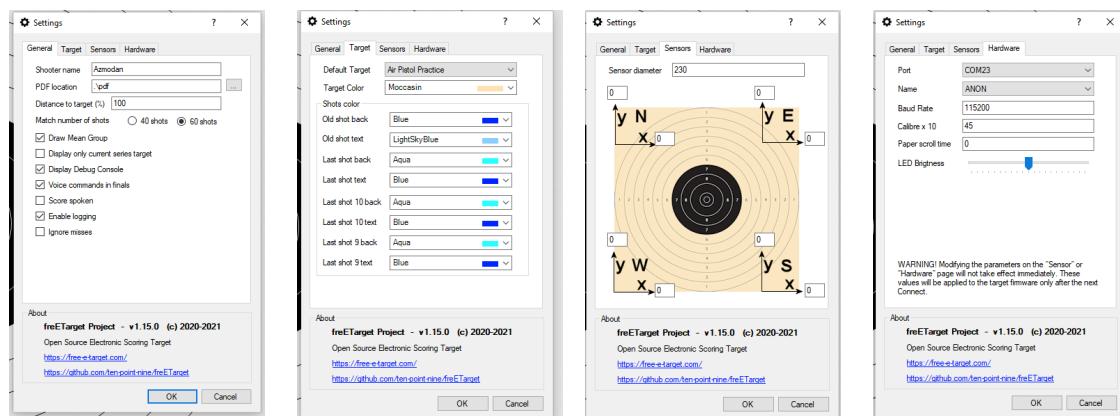


Figure 10: General Settings

Figure 11: Target Settings

Figure 12: Sensor Adjustment

Figure 13: Hardware Interface

Figure 10: This allows you to enter the shooter name and how information will be stored.

Figure 11: Choose the target you will be shooting against and the colours you will be using.

Figure 12: Fine tune the sensor position to adjust for assembly errors

Figure 13: Interface to the target hardware.

Press  to begin a session.

Refer to the Commissioning Instructions from the web site. This will give you a quick summary of how the system is working

TROUBLESHOOTING

The boards are tested before shipment, but a lot can happen between the last test and the first shot. If your system is not working, please follow the trouble shooting guide below before sending an email to freETarget.com

No Shots Registered	<ul style="list-style-type: none">• Check that the USB cable is attached• Check that the correct Serial port is set in the setup• Check that the wiring harness is attached to all of the sensors• Tap each of the sensors. Do the three LEDs blink?
Shots show up but in the wrong place	<ul style="list-style-type: none">• From the firing line, shoot a blank shot<ul style="list-style-type: none">○ Do the three LEDs blink?<ul style="list-style-type: none">■ Yes, set a new trip point■ No, Check all of the wiring• Verify that the sensors North – West are in the correct order
The shots show up but rotated 90 degrees	<ul style="list-style-type: none">• Verify the order of the sensors and correct
The shots are the mirror image left-right	<ul style="list-style-type: none">• The sensors are reversed. Switch the positions of NORTH-EAST and SOUTH-WEST

Appendix A: freETarget Components

